

Apacer In-Vehicle Embedded Modules

Features

- Single Mini PCI Express Socket for All Features
- Equips 2-Channel Individual CAN and 1-Channel J1708 Interfaces
- Vehicle Communication Protocols: OBD-II, J1939 and J1708
- Built-in u-blox NEO-M8 GPS Module (Optionally Support Untethered Dead Reckoning)
- Support GPS, GLONASS and BeiDou system
- Sensor Integrated: 3D Gyroscope and 3D Accelerometer



Introduction

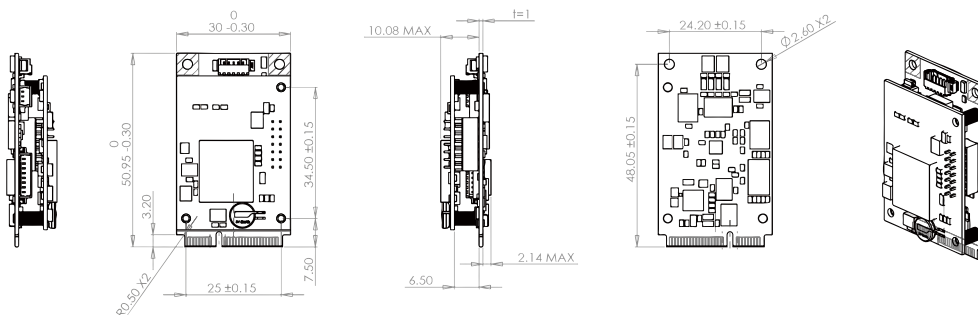
Apacer in-vehicle mini PCI Express card integrate CAN bus module and an extension GPS module.

In one mini PCI Express slot , this module can supply CAN (CAN bus 2.0 a/b, OBDII, J1939, J1708), 3D Gyroscope, 3D Accelerometer and u-blox GPS features. Apacer in-vehicle embedded modules optionally support UDR (Untethered Dead Reckoning GPS) function. UDR can combine inertial sensing data and GNSS signals to supply powerful positioning under poor GPS signal circumstances, such as signal loss in tunnels, driving in parking facilities, urban canyons, and where obstructed GPS signals hinder positioning. Apacer in-vehicle embedded module is the ideal solution for Fleet Management, Public Transportation Monitoring, Law Enforcement, In-Vehicle Digital Signage, Vehicle Data Collection, Vehicle Tracking, and Telematics System.

Specifications

| | |
|-----------------------------|--|
| Form Factor | Full Mini PCI Express Mini Card with Extension Board |
| Host Interface | USB 2.0 via Mini PCI Express Card Socket |
| CAN Interface Number | CAN for ISO 11898 x 2 Individual Channels J1708 x 1 Channel (Optional) |
| CAN Protocol | CAN 2.0 A/B, OBD-II (ISO 15765-4), J1939 and J1708 Support Mask and Identifier List Mode |
| Motion Sensor | 3D Gyroscope 3D Accelerometer |
| GPS Module | u-blox NEO-M8N or M8U Concurrent Reception Up to 3 GNSS System (GPS, GLONASS, BeiDou) Optionally Support Dead Reckoning Optionally Support External Antenna Optionally Support Hot Start Positioning |
| Identifier filtering | Mask and Identifier List Mode |
| Driver Support | Microsoft Windows 7 / 10 Linux Kernel 2.6 and 3.13 |
| SDK Support | Microsoft Windows 7 / 10 Linux Kernel 2.6 and 3.13 |
| Operation Temp. | -40° C ~ 85° C (without Hot Start Positioning Function) -20° C ~ 60° C (with Hot Start Positioning Function) |
| Vibration Test | Pass 7.69G@ 20~2000Hz, compliant with MIL-STD-810G |
| ESD Protection | 8kV Contact, 15kV air |
| Dimension | 50.9 x 30 x 13.2 mm |

Dimensions



Ordering Information

| Part Number | Description |
|-------------|--|
| APEFC-G10 | 2 Channels CAN 2.0 A/B, G-sensor and u-blox NEO-M8N GPS |
| APEFC-G30 | 2 Channels CAN 2.0 A/B, OBDII, G-sensor and u-blox NEO-M8N GPS |
| APEFC-G40 | 2 Channels CAN 2.0 A/B, OBDII, J1939, G-sensor and u-blox NEO-M8N GPS |
| APEFC-G50 | 2 Channels CAN 2.0 A/B, OBDII, J1939, 1 Channel J1708, G-sensor and u-blox NEO-M8N GPS |
| APEFC-R10 | 2 Channels CAN 2.0 A/B, G-sensor and u-blox NEO-M8U GPS |
| APEFC-R30 | 2 Channels CAN 2.0 A/B, OBDII, G-sensor and u-blox NEO-M8U GPS |
| APEFC-R40 | 2 Channels CAN 2.0 A/B, OBDII, J1939, G-sensor and u-blox NEO-M8U GPS |
| APEFC-R50 | 2 Channels CAN 2.0 A/B, OBDII, J1939, 1 Channel J1708, G-sensor and u-blox NEO-M8U GPS |